



Assessing Uncertainty in Regional Climate Experiments

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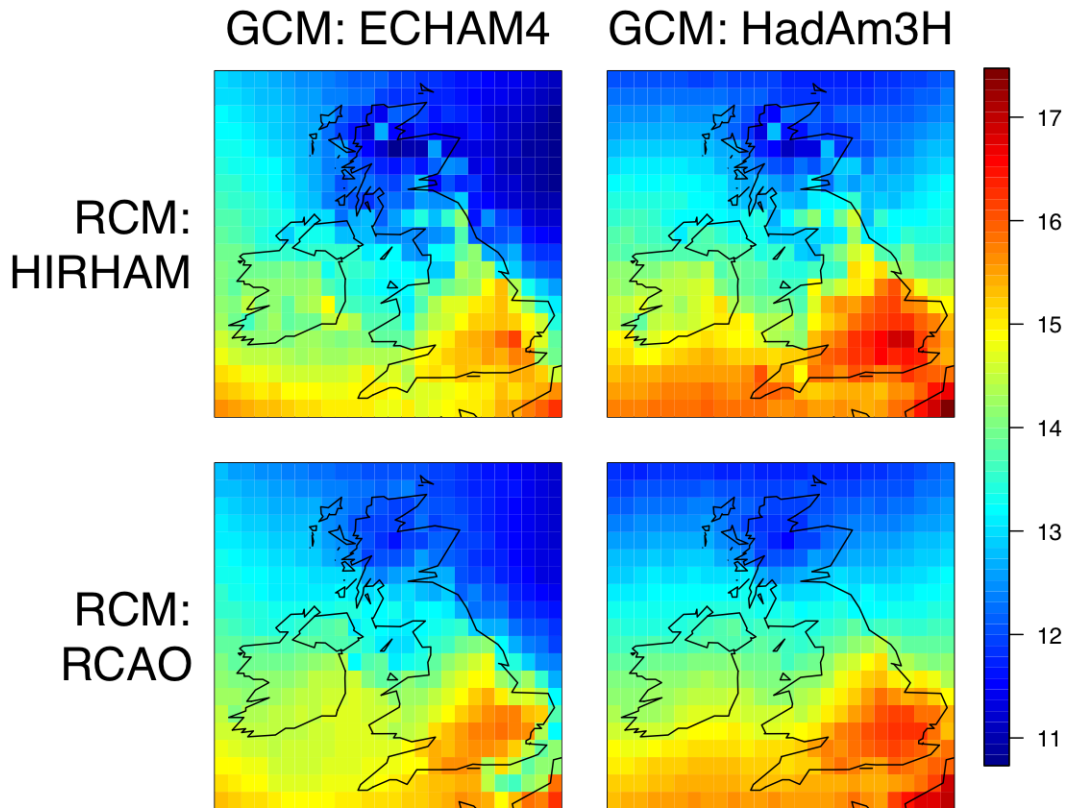


Supported by NSF ATM/DMS.

Goals

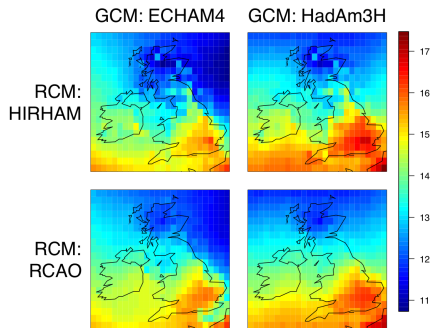
- Describe the distribution of model output.
- Understanding sources of variation.
 - GCM, RCM, GCM×RCM, Time Slice, etc.
- Combining model output – moving towards a scheme for weighting models.
- Recognizing that the climate model output represents spatial and/or spatial-temporal fields, we are developing methodology for a type of *functional ANOVA*.
 - Gaussian process ANOVA (Kaufman and Sain, 2007).

Functional ANOVA



- 2x2 “experiment”
 - 2 GCMs, 2 RCMs
 - PRUDENCE
- 1961-1990
- JJA average temp

Functional ANOVA



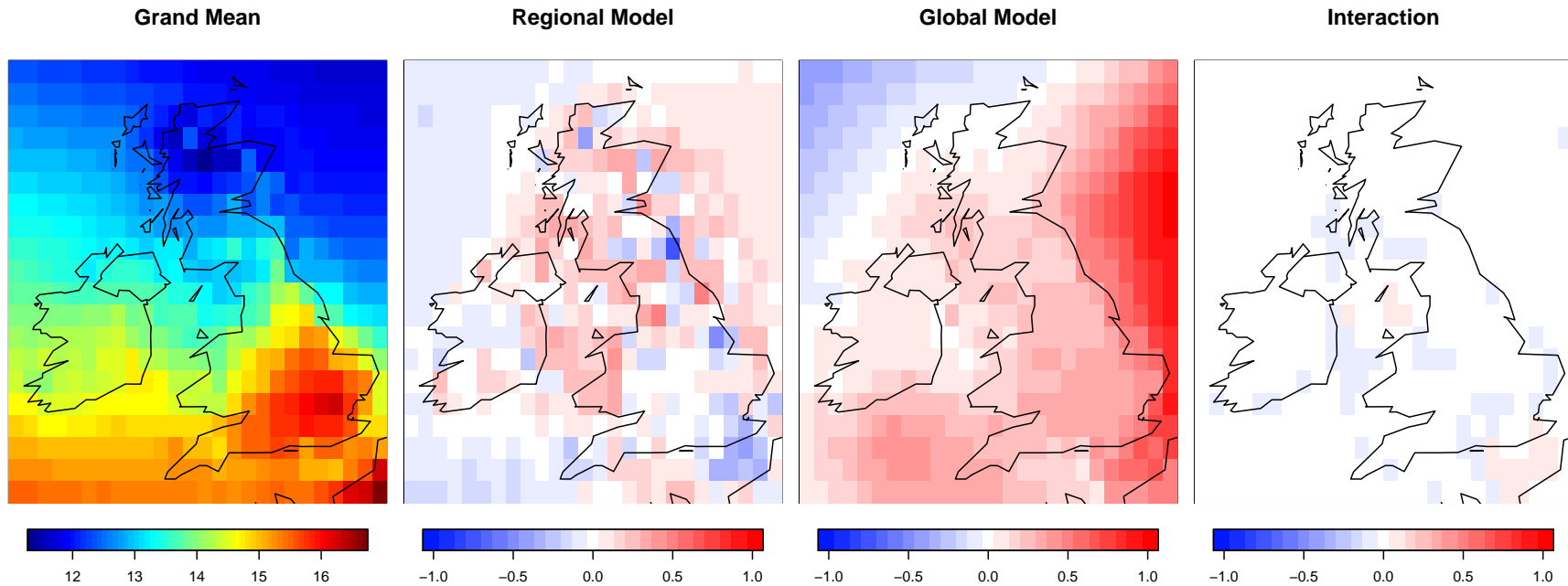
$$Z_{ijt}(s) = \mu_{ijt}(s) + \epsilon_{ijt}(s)$$

Output of RCM i , GCM j , at time t and location s = Expected/ "Climate" response + Spatially correlated residual/ "internal model variability"

$$\begin{aligned} \mu_{ijt}(s) &= \mu(s) + i\alpha(s) + j\beta(s) + ij(\alpha\beta)(s) + \gamma t, \\ &= \text{Common} + \text{RCM} + \text{GCM} + \text{Interaction} + \text{Time} \end{aligned}$$

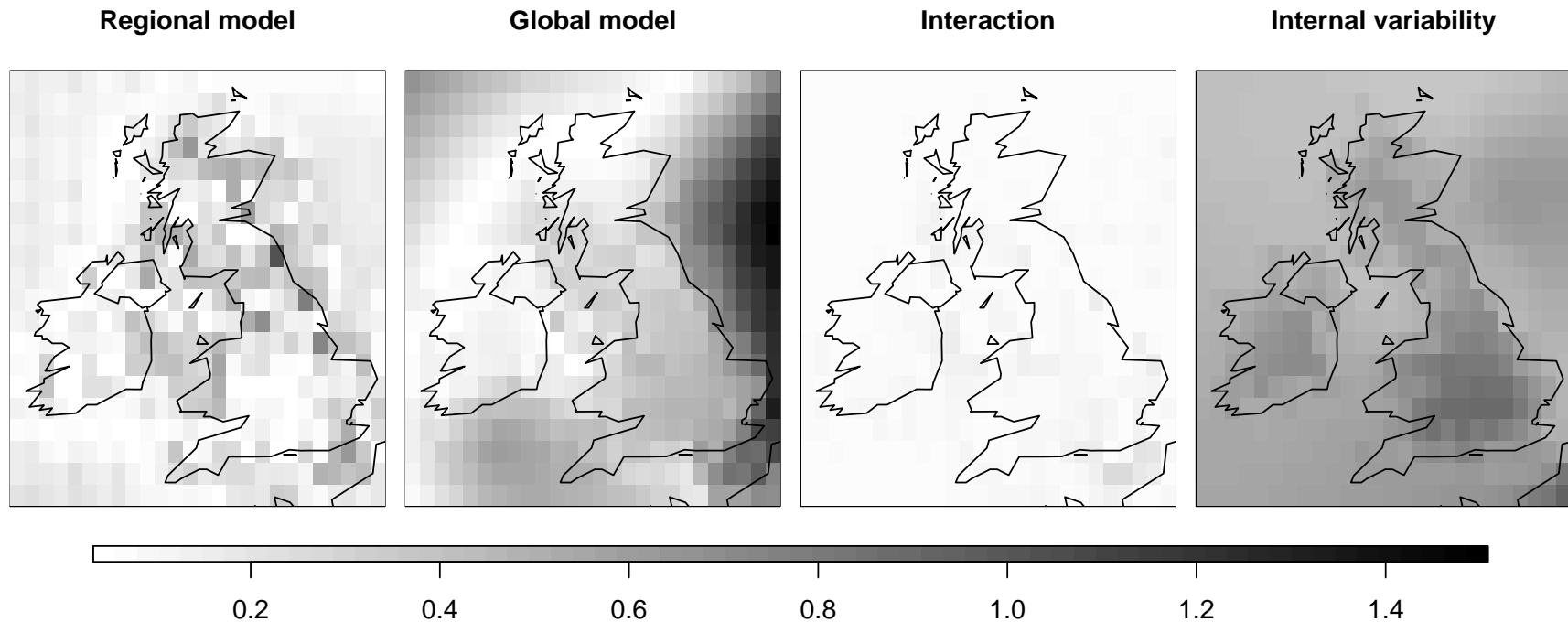
- $i, j = -1, 1$ (contrast coding)
- Hierarchical model with Gaussian process priors used for each effect.
- MCMC used to estimate parameters, posterior inference, etc.

Functional ANOVA



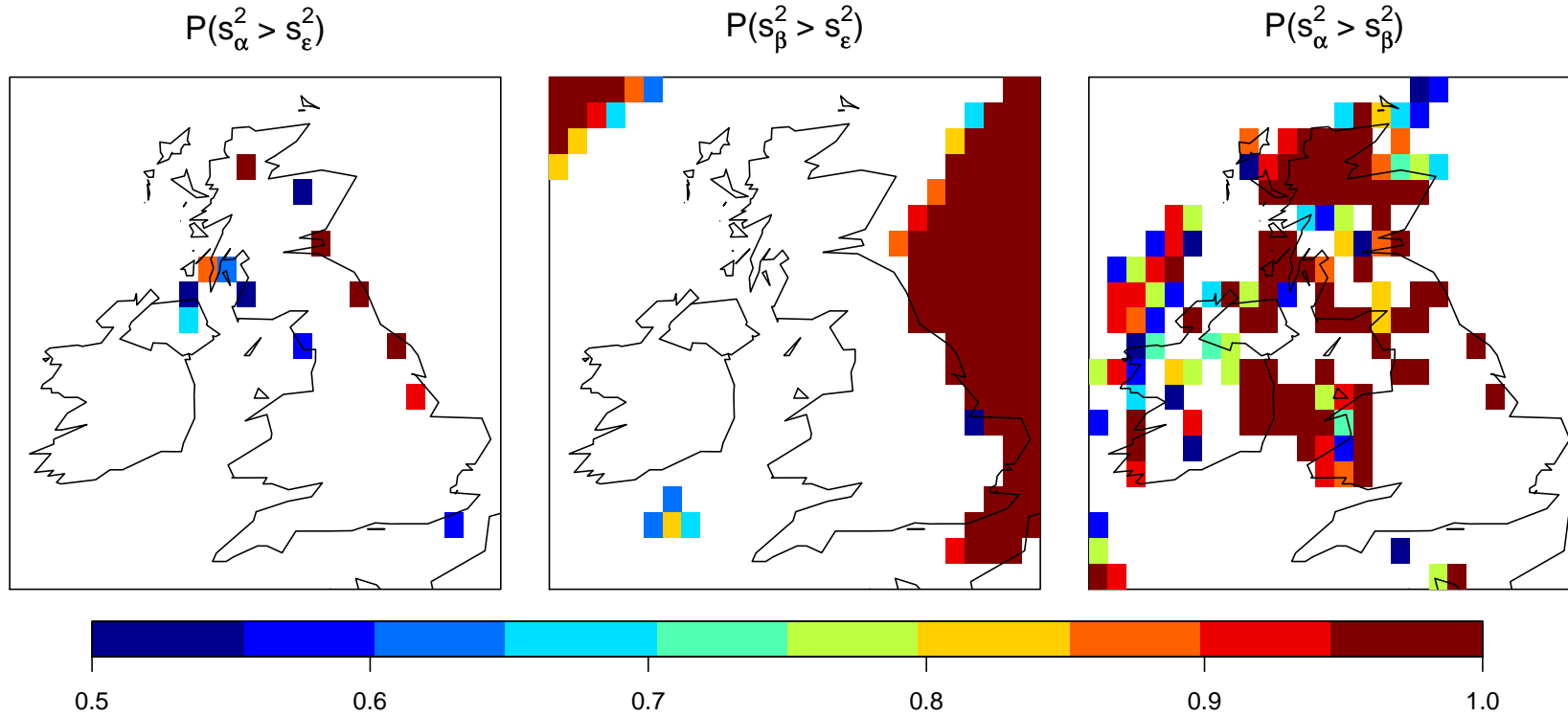
- Estimates of spatial effects.

Functional ANOVA



- Posterior mean of variance components.

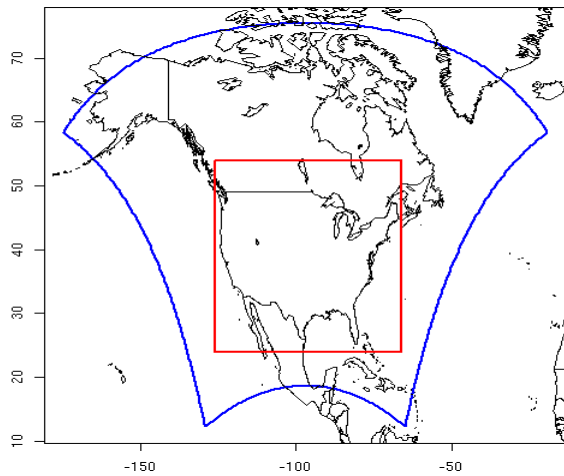
Functional ANOVA



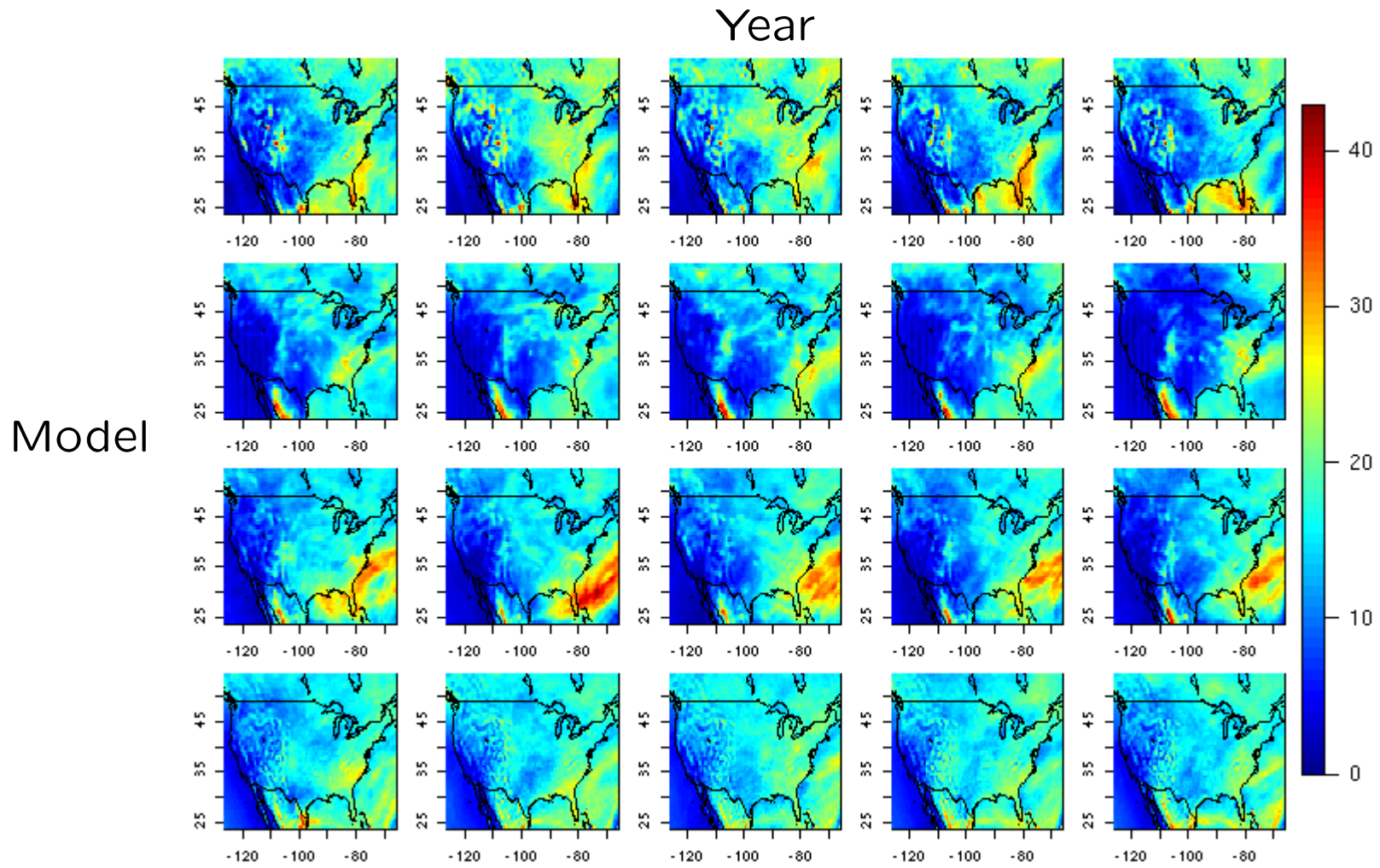
- Ratios of variances.

A Work in Progress

- 4 regional models.
- Total JJA precipitation, 1996-2000.



Model Output



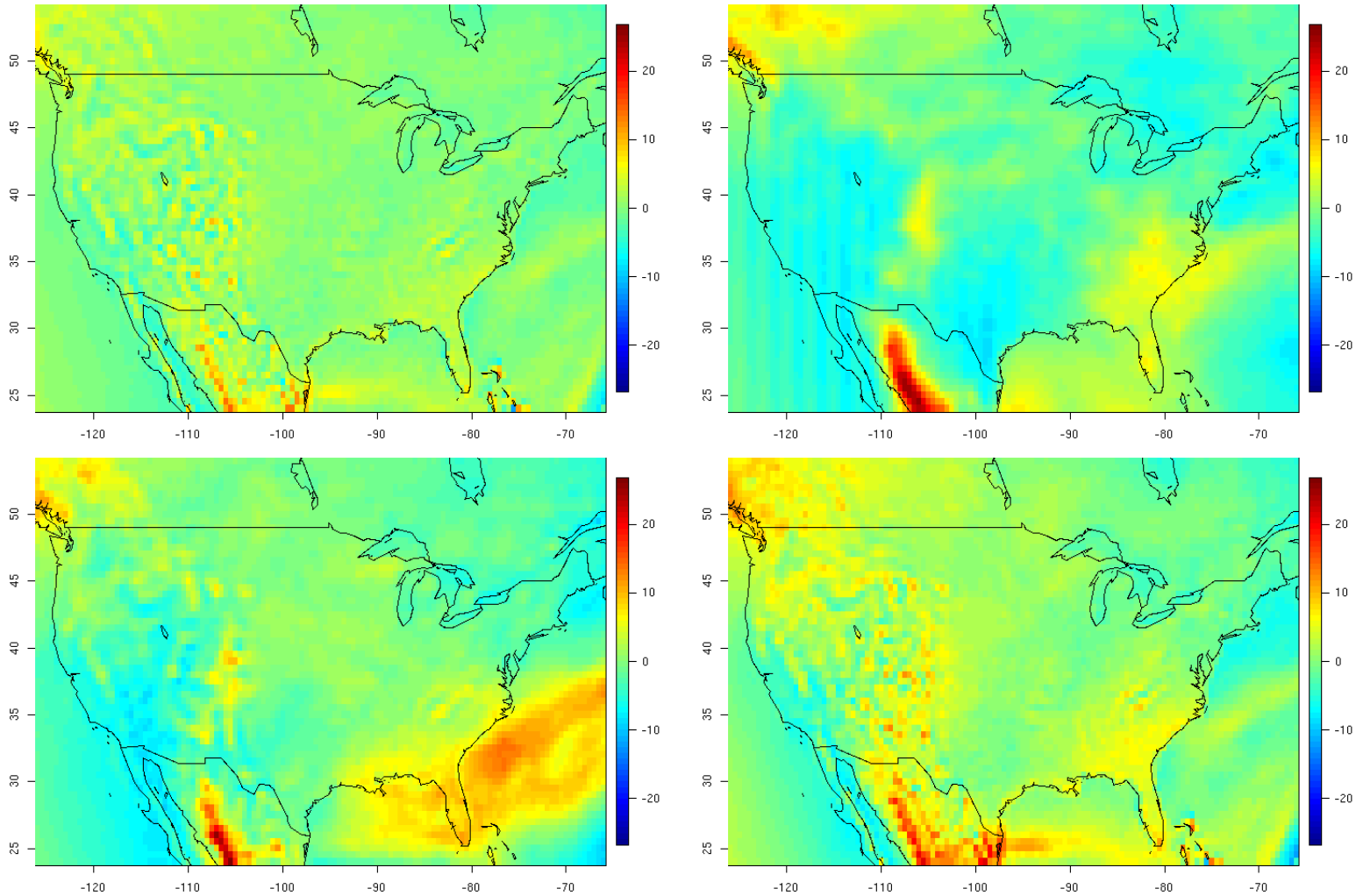
A Functional ANOVA Model

- A single-factor ANOVA model:

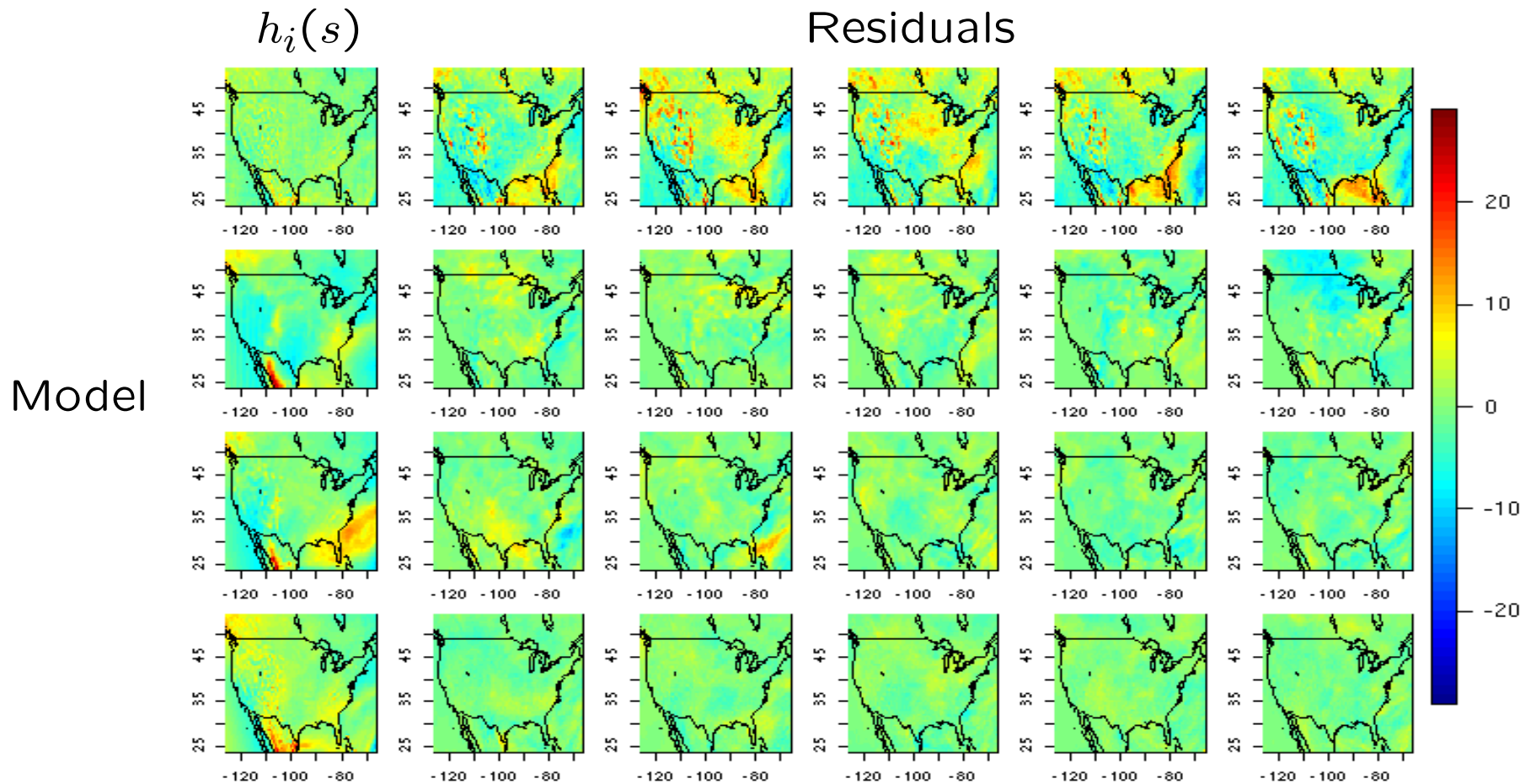
$$\begin{aligned} Z_{it}(s) &= \mu(s) + h_i(s) + \epsilon_{it}(s) \\ &= \text{Common} + \text{RCM} + \text{Error} \end{aligned}$$

- Hierarchical model with Gaussian prior (with spatial covariance) on $h_i(s)$.
- $\mu(s) = x(s)' \beta$ (based on NCEP).
- Errors $\epsilon_{it}(s)$ are also spatially correlated Gaussian.
- MCMC to estimate parameters, posterior inference, etc.

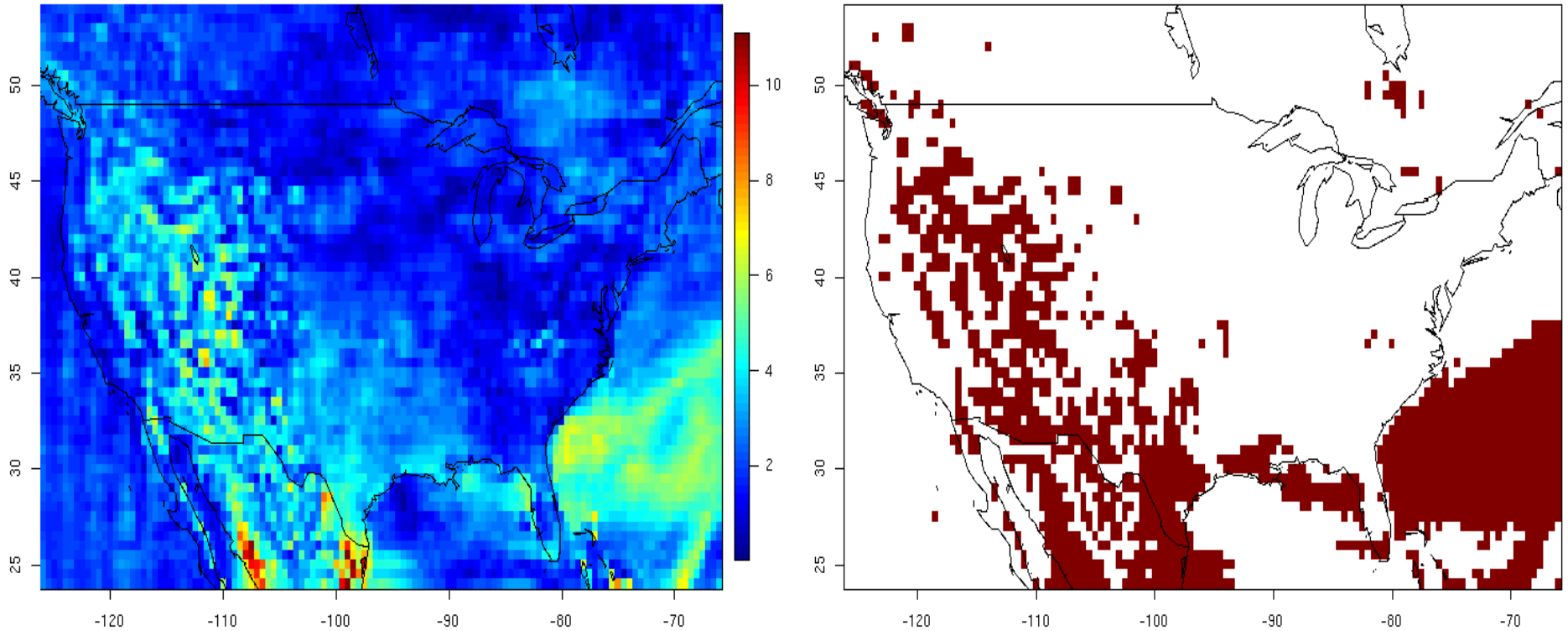
Results ($h_i(s)$, Posterior Means)



Results (A Posteriori Draw)

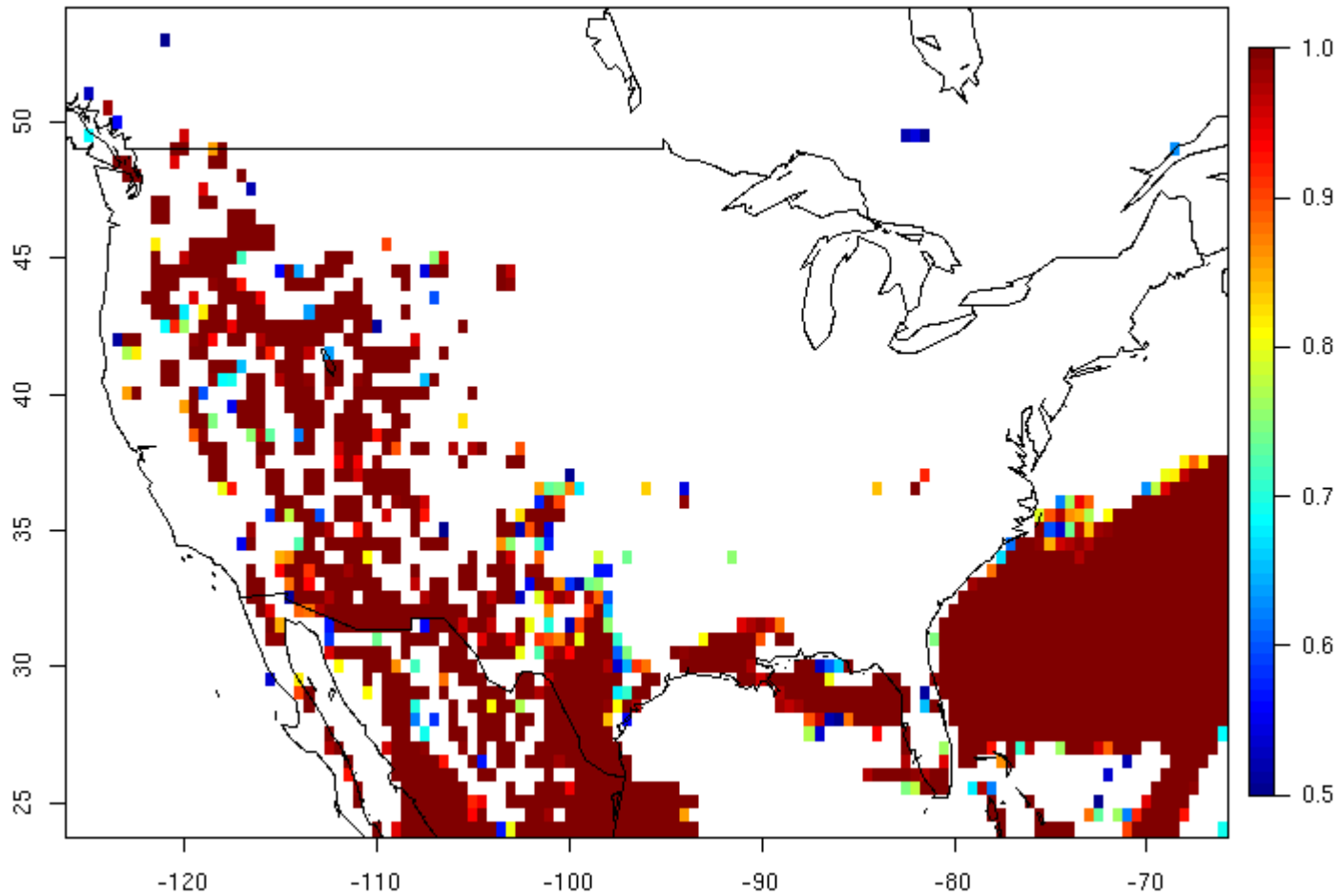


Results (A Posterior Draw)



- Compare s_h^2 to s^2 ; highlight where $s_h^2 > s^2$.

Results ($P[s_h^2 > s^2]$)



A Proposal for Combining Model Output

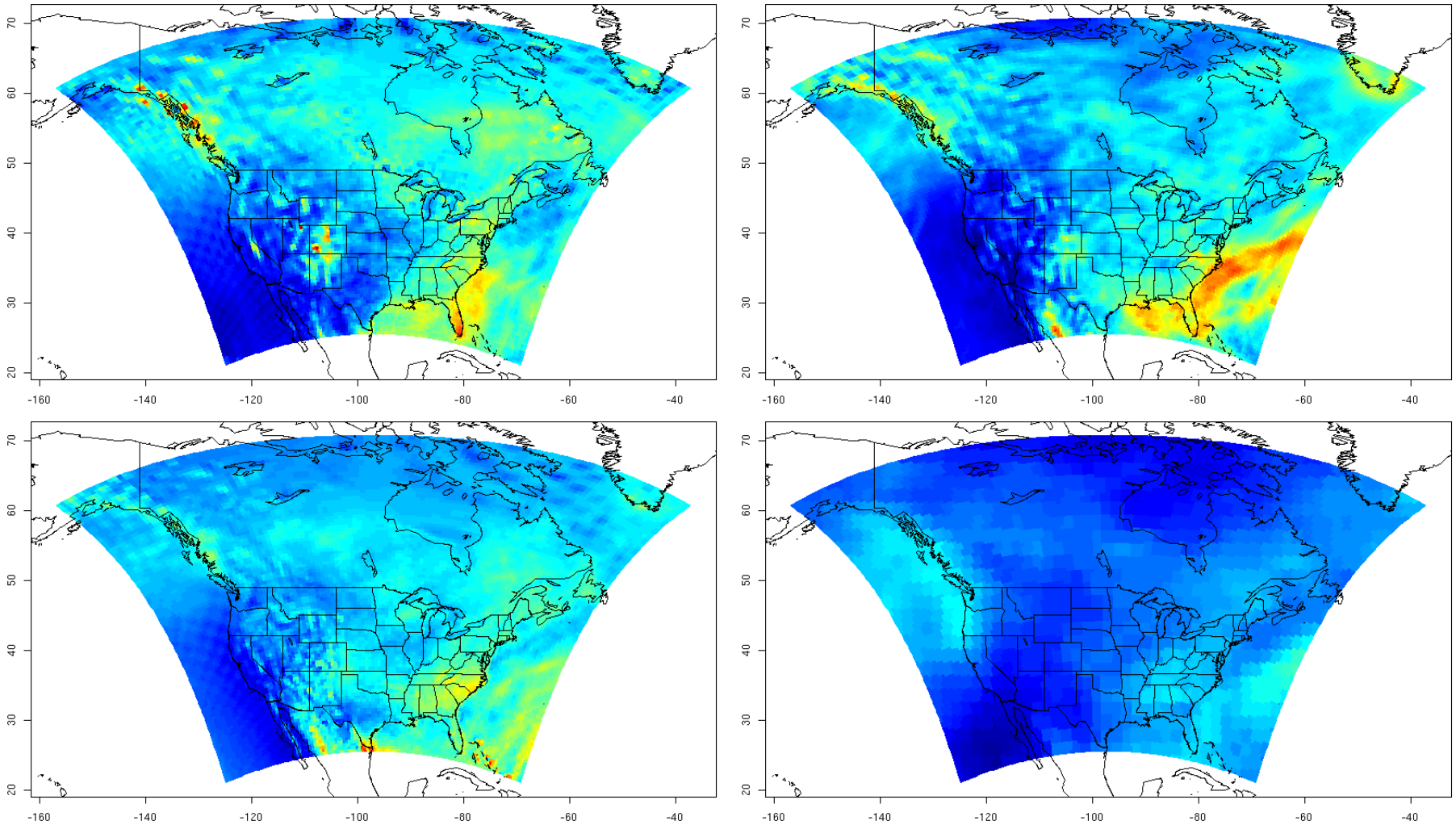
- Assumption of model output representing iid random draws may not be reasonable.
- A modified model:

$$\begin{aligned} Z_{it}(s) &= \mu(s) + h_i(s) + \epsilon_{it}(s) \\ &= \text{Common} + \text{RCM} + \text{Error} \end{aligned}$$

- The key difference is the prior on $h_1(s), h_2(s), h_3(s)$ is Gaussian with mean $\mathbf{0}$ and

$$\text{Var} \begin{pmatrix} h_1(s) \\ h_2(s) \\ h_3(s) \end{pmatrix} = \Sigma_h$$

A Proposal for Combining Model Output



A Proposal for Combining Model Output

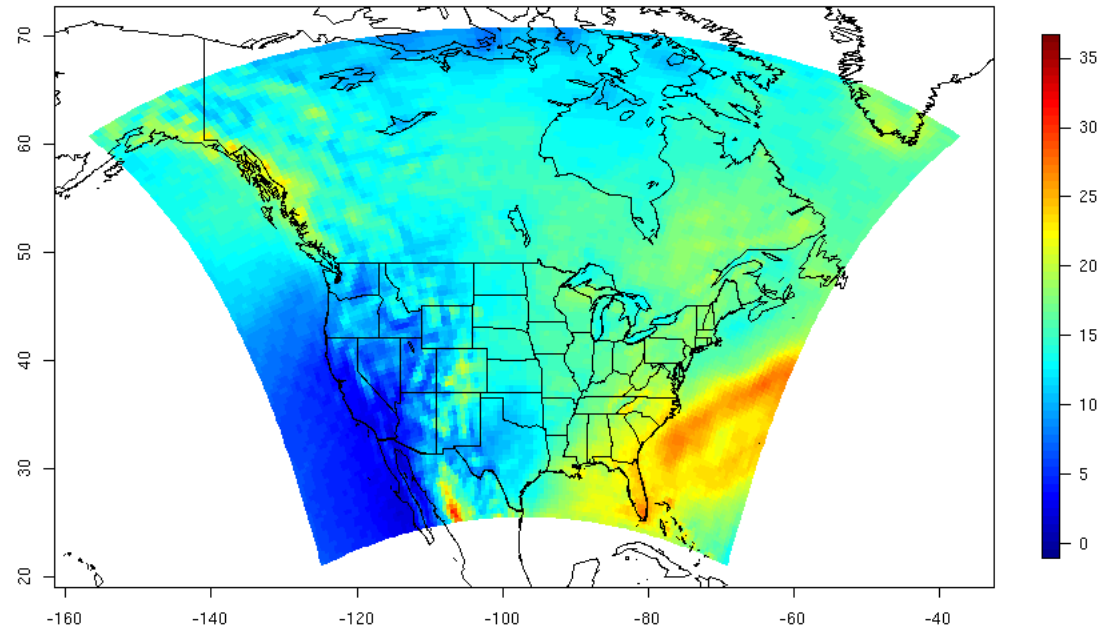
- The model-to-model covariance, Σ_h , can be used to create a linear combination of the $h_i(s)$.
- Assuming $E[h_i(s)] = \mu(s)$, it is easy to show that the \mathbf{w} that minimizes the variance of $\sum_i w_i h_i(s)$ is the solution to

$$\begin{pmatrix} \Sigma_h & -\mathbf{1} \\ \mathbf{1} & 0 \end{pmatrix} \begin{pmatrix} \mathbf{w} \\ \lambda \end{pmatrix} = \begin{pmatrix} \mathbf{0} \\ 1 \end{pmatrix}.$$

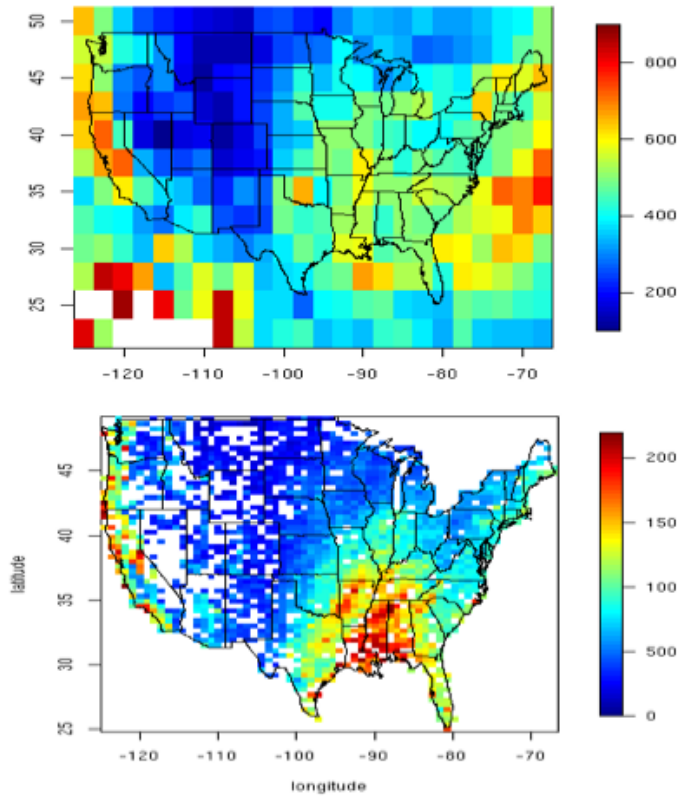
- Other ideas: maximize variance (principal components), etc.

A Proposal for Combining Model Output

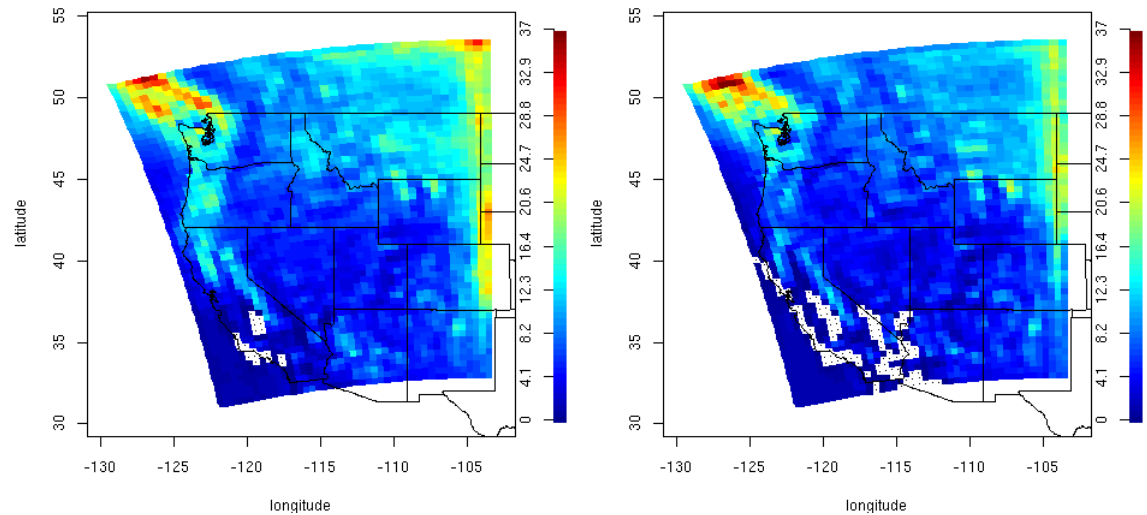
$$\hat{\Sigma}_h = \begin{pmatrix} 2.05 & 0.66 & 0.37 \\ & 0.94 & 0.50 \\ & & 1.37 \end{pmatrix}$$
$$\hat{\mathbf{w}} = \begin{pmatrix} 0.14 \\ 0.54 \\ 0.32 \end{pmatrix}$$



Extremes



- Spatial scaling of return levels.



- Comparing spatial distributions of extremes.

Questions?



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